

## ANEXO A – Algoritmo de Ghassaei

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//generalized wave freq detection with 38.5kHz sampling rate and interrupts
//by Amanda Ghassaei
//https://www.instructables.com/id/Arduino-Frequency-Detection/
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/*
 * This program is free software; you can redistribute it and/or modify
 * it under the terms of the GNU General Public License as published by
 * the Free Software Foundation; either version 3 of the License, or
 * (at your option) any later version.
 *
*/
//clipping indicator variables
boolean clipping = 0;

//data storage variables
byte newData = 0;
byte prevData = 0;
unsigned int time = 0;//keeps time and sends values to store in timer[]
occasionally
int timer[10];//storage for timing of events
int slope[10];//storage for slope of events
unsigned int totalTimer;//used to calculate period
unsigned int period;//storage for period of wave
byte index = 0;//current storage index
float frequency;//storage for frequency calculations
int maxSlope = 0;//used to calculate max slope as trigger point
int newSlope;//storage for incoming slope data

//variables for decided whether you have a match
byte noMatch = 0;//counts how many non-matches you've received to reset
variables if it's been too long
byte slopeTol = 3;//slope tolerance- adjust this if you need
int timerTol = 10;//timer tolerance- adjust this if you need

//variables for amp detection
unsigned int ampTimer = 0;
byte maxAmp = 0;
byte checkMaxAmp;
byte ampThreshold = 30;//raise if you have a very noisy signal

void setup(){

    Serial.begin(9600);

    pinMode(13,OUTPUT);//led indicator pin
    pinMode(12,OUTPUT);//output pin

    cli();//disable interrupts
}

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//set up continuous sampling of analog pin 0 at 38.5kHz

//clear ADCSRA and ADCSRB registers
ADCSRA = 0;
ADCSRB = 0;

ADMUX |= (1 << REFS0); //set reference voltage
ADMUX |= (1 << ADLAR); //left align the ADC value- so we can read highest
8 bits from ADCH register only

ADCSRA |= (1 << ADPS2) | (1 << ADPS0); //set ADC clock with 32 prescaler-
16mHz/32=500kHz
ADCSRA |= (1 << ADATE); //enable auto trigger
ADCSRA |= (1 << ADIE); //enable interrupts when measurement complete
ADCSRA |= (1 << ADEN); //enable ADC
ADCSRA |= (1 << ADSC); //start ADC measurements

sei();//enable interrupts
}

ISR(ADC_vect) {//when new ADC value ready

PORTB &= B11101111;//set pin 12 low
prevData = newData;//store previous value
newData = ADCH;//get value from A0
if (prevData < 127 && newData >=127){//if increasing and crossing
midpoint
    newSlope = newData - prevData;//calculate slope
    if (abs(newSlope-maxSlope)<slopeTol){//if slopes are ==
        //record new data and reset time
        slope[index] = newSlope;
        timer[index] = time;
        time = 0;
        if (index == 0){//new max slope just reset
            PORTB |= B00010000;//set pin 12 high
            noMatch = 0;
            index++;//increment index
        }
        else if (abs(timer[0]-timer[index])<timerTol && abs(slope[0]-
newSlope)<slopeTol){//if timer duration and slopes match
            //sum timer values
            totalTimer = 0;
            for (byte i=0;i<index;i++){
                totalTimer+=timer[i];
            }
            period = totalTimer;//set period
            //reset new zero index values to compare with
            timer[0] = timer[index];
            slope[0] = slope[index];
            index = 1;//set index to 1
            PORTB |= B00010000;//set pin 12 high
            noMatch = 0;
        }
    }
}
}

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        else{//crossing midpoint but not match
            index++; //increment index
            if (index > 9){
                reset();
            }
        }
    }
    else if (newSlope>maxSlope){//if new slope is much larger than max
slope
        maxSlope = newSlope;
        time = 0;//reset clock
        noMatch = 0;
        index = 0;//reset index
    }
    else{//slope not steep enough
        noMatch++; //increment no match counter
        if (noMatch>9){
            reset();
        }
    }
}

if (newData == 0 || newData == 1023){//if clipping
    PORTB |= B00100000;//set pin 13 high- turn on clipping indicator led
    clipping = 1;//currently clipping
}

time++;//increment timer at rate of 38.5kHz

ampTimer++;//increment amplitude timer
if (abs(127-ADCH)>maxAmp){
    maxAmp = abs(127-ADCH);
}
if (ampTimer==1000){
    ampTimer = 0;
    checkMaxAmp = maxAmp;
    maxAmp = 0;
}
}

void reset(){//clear out some variables
    index = 0;//reset index
    noMatch = 0;//reset match counter
    maxSlope = 0;//reset slope
}

void checkClipping(){//manage clipping indicator LED
    if (clipping){//if currently clipping
        PORTB &= B11011111;//turn off clipping indicator led
        clipping = 0;
    }
}

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void loop(){
    checkClipping();

    if (checkMaxAmp>ampThreshold){
        frequency = 38462/float(period); //calculate frequency timer rate/period

        //print results
        Serial.print(frequency);
        Serial.println(" hz");
    }

    delay(100); //delete this if you want

    //do other stuff here
}
```